

Sine Rodless Cylinder/Basic Type

Series *REA*

ø25, ø32, ø40, ø50, ø63

How to Order



Basic type

REA 25 - **300** -

Sine rodless cylinder
(Basic type)

Bore size

25	25 mm
32	32 mm
40	40 mm
50	50 mm
63	63 mm

Stroke (mm)

Refer to "Standard Stroke" below.

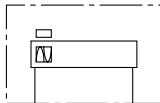
Port thread type

Symbol	Type	Bore size
Nil	Rc	25, 32, 40
TN	NPT	50, 63
TF	G	32, 50, 63

Made to Order
Refer to the table below
for details.

Specifications

Bore size (mm)	25	32	40	50	63
Fluid	Air				
Proof pressure	1.05 MPa				
Maximum operating pressure	0.7 MPa				
Minimum operating pressure	0.18 MPa				
Ambient and fluid temperature	-10 to 60°C (No freezing)				
Piston speed (Max.) ^{Note)}	50 to 300 mm/s				
Lubrication	Not required (Non-lube)				
Stroke length tolerance	0 to 250 st: ⁺¹ ₀ , 251 to 100 st: ^{+1.4} ₀ , 1001 st or longer: ^{+1.8} ₀				
Holding force	363	588	922	1,470	2,260



JIS Symbol

Note) Piston speed above indicates the maximum speed. It takes approximately 0.5 seconds (for one side) after the body moves from the stroke end until it goes through the cushion stroke, while it takes approximately 1 second for both sides.

Standard Stroke

Bore size (mm)	Standard stroke (mm)	Maximum manufacturable stroke (mm)
25	200, 250, 300, 350, 400, 450, 500, 600, 700, 800	4000
32	200, 250, 300, 350, 400, 450, 500, 600, 700, 800	
40	200, 250, 300, 350, 400, 450, 500, 600, 700, 800, 900, 1000	5000
50	200, 250, 300, 350, 400, 450, 500, 600, 700, 800, 900, 1000	6000
63	200, 250, 300, 350, 400, 450, 500, 600, 700, 800, 900, 1000	

Note 1) Intermediate stroke is available by the 1 mm interval.

Note 2) Strokes over 2000 mm are available as made-to-order. (Refer to -XB11.)

Mass

Bore size (mm)	25	32	40	50	63
Basic mass	0.71	1.34	2.15	3.4	5.7
Additional mass per each 50 mm of stroke	0.05	0.07	0.08	0.095	0.12

Calculation: (Example) **REA32-500** • Basic mass1.34 (kg)
 • Additional mass0.07 (kg/50 st)
 • Cylinder stroke500 (st)
 1.34 + 0.07 x 500 ÷ 50 = 2.04 kg

Made to Order Specifications

(For details, refer to pages 1851 to 1954.)

Symbol	Specifications
-XB11	Long stroke type
-XC24	With magnet shielding plate
-XC57	With floating joint
-X206	Additional moving element mounting taps
-X210	Non-lubricated exterior specifications
-X324	Non-lubricated exterior specifications with dust seal
-X168	Helical insert thread specifications

Refer to "Pneumatic Clean Series" catalog for clean room specifications.

REA

REB

REC

C□Y

C□X

MQ

RHC

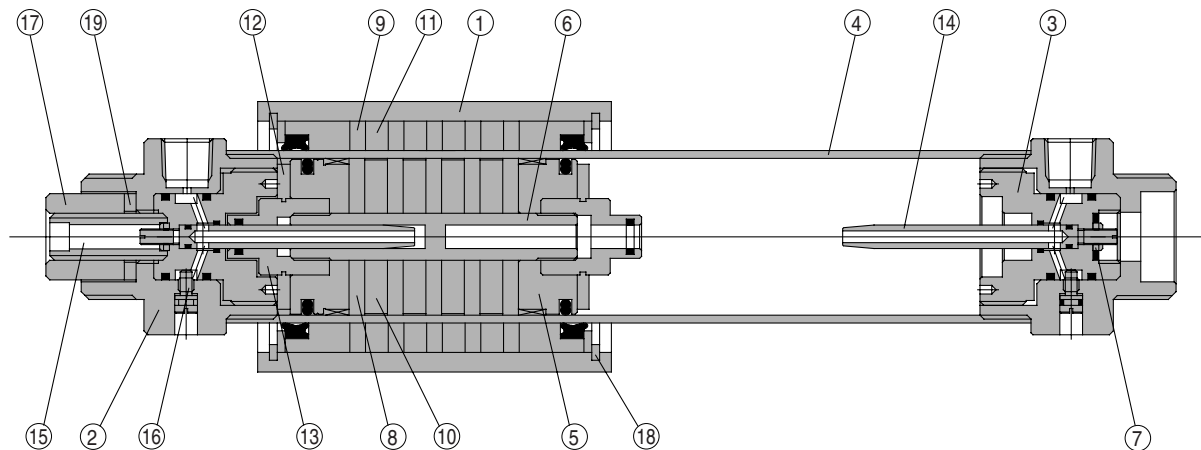
RZQ

D-□

-X□

Individual
-X□

Construction



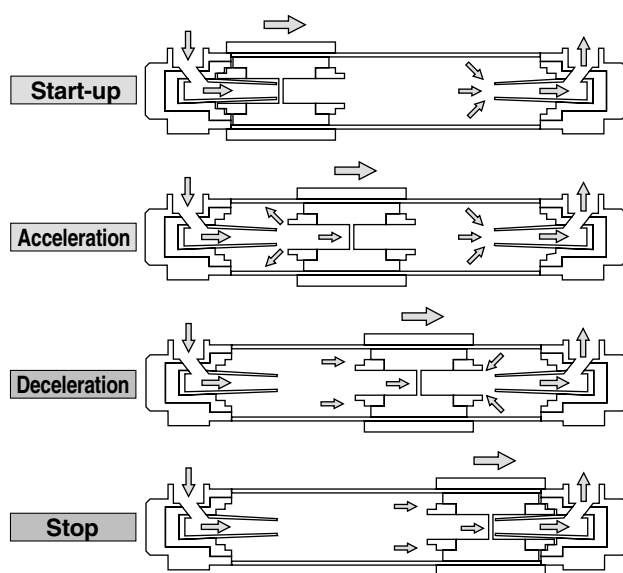
Component Parts

No.	Description	Material	Note
1	Body	Aluminum alloy	Anodized
2	Head cover	Aluminum alloy	Anodized
3	Cushion ring holder	Aluminum alloy	Chromated
4	Cylinder tube	Stainless steel	
5	Piston	Aluminum alloy	Chromated
6	Shaft	Stainless steel	
7	Lock nut B	Carbon steel	Nickel plated
8	Piston side yoke	Rolled steel plate	Zinc chromated
9	External slider side yoke	Rolled steel plate	Zinc chromated
10	Magnet A	—	

Component Parts

No.	Description	Material	Note
11	Magnet B	—	
12	Bumper	Urethane rubber	
13	Cushion seal holder	Aluminum alloy	Chromated
14	Cushion ring	Brass	Electroless nickel plated
15	Adjusting screw	Carbon steel	Nickel plated
16	Stopper bolt	Carbon steel	Nickel plated
17	Lock nut A	Carbon steel	Nickel plated
18	Retaining ring	Carbon tool steel	
19	Spring washer	Steel wire	

Working principle



Start-up/Acceleration

The driving air from the cylinder port passes through the inside of the cushion ring, and flows into the left chamber of the drive piston from the clearance between the cushion seal and the U-shaped groove in the outer surface of the cushion ring. Further, the exhaust air in the right chamber of the drive piston passes from inside the hollow cushion ring through the cylinder port and is released to the atmosphere by the drive solenoid valve.

When the differential pressure (thrust) generated on either side of the drive piston becomes larger than the starting resistance of the machinery, the drive piston begins to move to the right. As the drive piston moves to the right, the U-shaped groove in the outer surface of the cushion ring gradually becomes deeper, a flow corresponding to the drive speed of the drive piston flows into the left chamber of the drive piston, and the drive piston proceeds to accelerate. The U-shaped groove is machined into the cushion ring in such a way that this acceleration process can proceed smoothly (as a sine function).

Deceleration/Stop

In conventional cushion mechanisms, when the cushion seal installed on the drive piston is pushed into the cushion ring at the right stroke end, the drive piston's right chamber is pressurized and a sudden braking force is generated. However, in a sine rodless cylinder, due to the U-shaped groove provided on the outer surface of the cushion ring, whose depth changes as a sine function, a large quantity of the air in the cushion chamber is discharged when the cushion seal is pushed in, and a sudden braking force is not generated. With the progression of the cushion stroke, the discharge flow from the cushion chamber is restricted, and therefore, a soft stop is achieved at the stroke end.