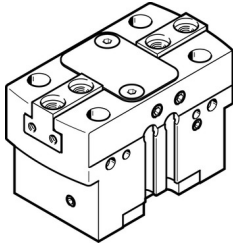


Parallel gripper HGPT-16-A-B

Part number: 560192

FESTO



Data sheet

Feature	Value
Size	16
Stroke per gripper jaws	3 mm
Max. replacement accuracy	≤ 0.2 mm
Max. angular gripper jaw backlash ax, ay	≤ 0.1 deg
Max. gripper jaw backlash Sz	≤ 0.02 mm
Rotationally symmetrical	≤ 0.2 mm
Repetition accuracy, gripper	≤ 0.03 mm
Short type code	HGPT
Number of gripper jaws	2
Mounting position	optional
Mode of operation	Double-acting
Gripper function	Parallel
Design	Wedge-shaped drive Force pilot operated motion sequence
Position detection	Via proximity switch
Symbol	00991894
Total gripper force, opening, 6 bar	120 N
Total gripper force, closing, 6 bar	106 N
Operating pressure	3 bar ... 8 bar
Operating pressure of blocked air	0 bar ... 0.5 bar
Max. operating frequency of gripper	≤ 3 Hz
Min. opening time at 6 bar	9 ms
Min. closing time at 6 bar	11 ms
Operating medium	Compressed air to ISO 8573-1:2010 [7:4:4]
Note on operating and pilot medium	Lubricated operation possible (in which case lubricated operation will always be required)
Corrosion resistance class CRC	2 - Moderate corrosion stress
Degree of protection	IP40
Ambient temperature	5 °C ... 60 °C
Gripper force per gripper jaw, opening, 6 bar	60 N
Gripper force per gripper jaw, closing, 6 bar	53 N
Mass moment of inertia	0.141 kgcm ²
Max. force on gripper jaw Fz static	200 N
Max. torque at gripper Mx static	10 Nm
Max. torque at gripper My static	12 Nm
Max. torque at gripper Mz static	6 Nm

Feature	Value
Lubrication interval for guide components	5 MioCyc
Max. mass per external gripper finger	40 g
Product weight	85 g
Type of mounting	Either: Via female thread and centring sleeve Via through-hole and centring sleeve Via through-hole and dowel pin Via female thread and dowel pin
Pneumatic connection, blocked air	M3
Pneumatic connection	M5
Note on materials	Copper/PTFE-free RoHS-compliant
Material cover cap	High-alloy stainless steel
Material housing	Aluminium Anodised
Material gripper jaws	Steel Hardened