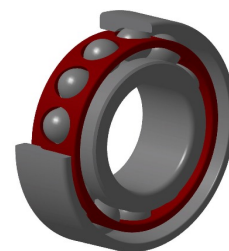


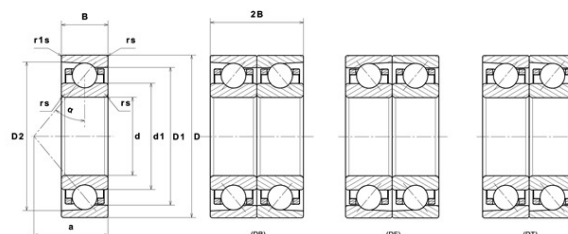
PDF technical sheet 7020HVUJ84



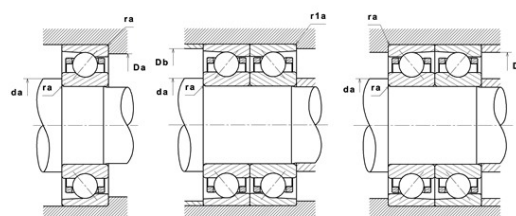
High precision angular contact ball bearings

High precision angular contact ball bearing, laminated resin cage centred on outer ring

Product definition	
d	100 mm
D	150 mm
B	24 mm
d1	115.80 mm
D1	134.20 mm
D2	141.51 mm
a	41 mm
Contact angle, α	25 °
rs min	1.50 mm
r1s min	0.60 mm
f0	16.177
Precision class	P4
Mass	1.25 kg
Brand	SNR



Product performance	
Dynamic load, C	71.20 kN
Static load, C0	73.40 kN
Fatigue limit load, Cu	3.70 kN
Nlim (oil)	13,000 Tr/min
Nlim (grease)	8,400 Tr/min
Axial displacement K Factor	0.43
Preload level	8
Peload value	1,880 kN
axial rigidity	425 N/ μ m
radial rigidity	852 N/ μ m
Min operating temperature, Tmin	-30 °C
Max operating temperature, Tmax	120 °C
Characteristic cage frequency, FTF	0.45 Hz
Characteristic rolling element frequency, BSF	8.19 Hz
Characteristic outer ring frequency, BPF0	9.80 Hz
Characteristic inner ring frequency, BPF1	12.20 Hz



Abutment dimensions

da min	108.50 mm
db min	108.50 mm
Da max	141.50 mm
Db max	141.50 mm
r1a max	0.60 mm
ra max	1.50 mm
D6	120.70 mm

Calculation factors

Equivalent dynamic radial load

$$P = X \cdot Fr + Y \cdot Fa$$

Series			e	Single or DT bearing arrangement				DB or DF arrangement			
				Fa / Fr ≤ e		Fa / Fr > e		Fa / Fr ≤ e		Fa / Fr > e	
				X	Y	X	Y	X	Y	X	Y
70 (NTN & SNR) 72 (NTN & SNR) 78 (NTN) 79 (NTN) 719 (SNR)	15°	0.178	0.38	1	0	0.44	1.47	1	1.65	0.72	2.39
		0.357	0.4				1.4		1.57		2.28
		0.714	0.43				1.3		1.46		2.11
		1.07	0.46				1.23		1.38		2
		1.43	0.47				1.19		1.34		1.93
		2.14	0.5				1.12		1.26		1.82
		3.57	0.55				1.02		1.14		1.66
		5.35	0.56						1.12		1.63
		7.14	0.56				1		1.12		1.63
	25°		0.68			0.41	0.87		0.92	0.67	1.41
	30°		0.8			0.39	0.76		0.78	0.63	1.24

Equivalent static radial load

$$P_0 = X_0 \cdot Fr + Y_0 \cdot Fa$$

Series			Single or DT bearing arrangement		DB or DF arrangement	
			X ₀	Y ₀	X ₀	Y ₀
70 (NTN & SNR) 72 (NTN & SNR) 78 (NTN) 79 (NTN) 719 (SNR)	15°		0.5	0.46	1	0.92
	25°			0.38		0.76
	30°			0.33		0.66

For single or DT bearing arrangement :

If $P_0 < Fr$, then use $P_0 = Fr$