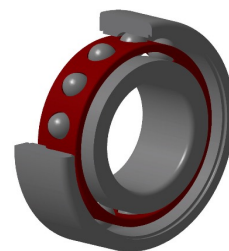


PDF technical sheet ML7009HVUJ74S

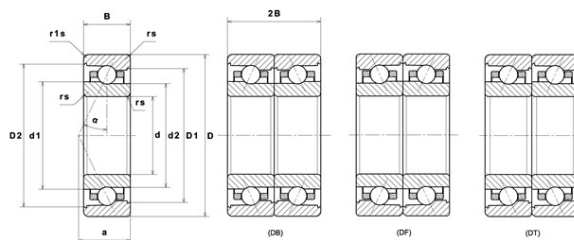


High precision angular contact ball bearings

High precision angular contact ball bearing, high speed series ML, laminated resin cage centred on outer ring

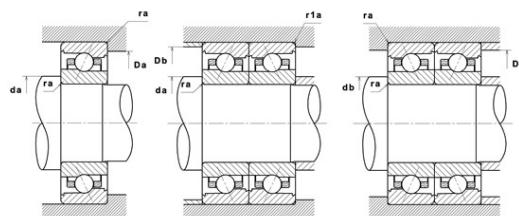
Product definition

d	45 mm
D	75 mm
B	16 mm
d1	54.70 mm
d2	52.40 mm
D1	66.31 mm
D2	68.46 mm
a	22 mm
Contact angle, α	25 °
rs min	1 mm
r1s min	0.60 mm
f0	8.344
Precision class	P4S
Mass	0.24 kg
Brand	SNR



Product performance

Dynamic load, C	10.30 kN
Static load, C0	6.70 kN
Fatigue limit load, Cu	0.40 kN
Nlim (oil)	33,000 Tr/min
Nlim (grease)	23,000 Tr/min
Axial displacement K Factor	0.68
Preload level	7
Peloid value	90 kN
axial rigidity	92 N/ μ m
radial rigidity	205 N/ μ m
Min operating temperature, Tmin	-30 °C
Max operating temperature, Tmax	120 °C
Characteristic cage frequency, FTF	0.45 Hz
Characteristic rolling element frequency, BSF	9.17 Hz
Characteristic outer ring frequency, BPF0	9.92 Hz
Characteristic inner ring frequency, BPF1	12.08 Hz



Abutment dimensions

da min	50.50 mm
db min	50.50 mm
Da max	69.50 mm
Db max	69.50 mm
r1a max	0.60 mm
ra max	1 mm
D6	56.90 mm

Calculation factors

Equivalent dynamic radial load

$$P = X \cdot Fr + Y \cdot Fa$$

Series			e	Single or DT bearing arrangement				DB or DF arrangement			
				Fa / Fr ≤ e		Fa / Fr > e		Fa / Fr ≤ e		Fa / Fr > e	
				X	Y	X	Y	X	Y	X	Y
70 (NTN & SNR) 72 (NTN & SNR) 78 (NTN) 79 (NTN) 719 (SNR)	15°	0.178	0.38	1	0	0.44	1.47	1	1.65	0.72	2.39
		0.357	0.4				1.4		1.57		2.28
		0.714	0.43				1.3		1.46		2.11
		1.07	0.46				1.23		1.38		2
		1.43	0.47				1.19		1.34		1.93
		2.14	0.5				1.12		1.26		1.82
		3.57	0.55				1.02		1.14		1.66
		5.35	0.56						1.12		1.63
		7.14	0.56				1		1.12		1.63
	25°		0.68				0.41		0.87		1.41
	30°		0.8				0.39		0.76		1.24

Equivalent static radial load

$$Po = Xo \cdot Fr + Yo \cdot Fa$$

Series			Single or DT bearing arrangement		DB or DF arrangement	
			X ₀	Y ₀	X ₀	Y ₀
70 (NTN & SNR) 72 (NTN & SNR) 78 (NTN) 79 (NTN) 719 (SNR)	15°		0.5	0.46	1	0.92
	25°			0.38		0.76
	30°			0.33		0.66

For single or DT bearing arrangement :

If $Po < Fr$, then use $Po = Fr$