

PDF technical sheet ML7010HVUJ84S



High precision angular contact ball bearings

High precision angular contact ball bearing, high speed series ML, laminated resin cage centred on outer ring

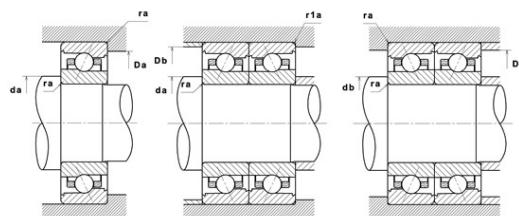
Product definition

d	50 mm
D	80 mm
B	16 mm
d1	59.70 mm
d2	57.40 mm
D1	71.41 mm
D2	73.81 mm
a	23 mm
Contact angle, α	25 °
rs min	1 mm
r1s min	0.60 mm
f0	8.438
Precision class	P4S
Mass	0.26 kg
Brand	SNR



Product performance

Dynamic load, C	11.10 kN
Static load, C0	7.70 kN
Fatigue limit load, Cu	0.46 kN
Nlim (oil)	30,000 Tr/min
Nlim (grease)	21,000 Tr/min
Axial displacement K Factor	0.62
Preload level	8
Peloid value	280 kN
axial rigidity	150 N/ μ m
radial rigidity	325 N/ μ m
Min operating temperature, Tmin	-30 °C
Max operating temperature, Tmax	120 °C
Characteristic cage frequency, FTF	0.46 Hz
Characteristic rolling element frequency, BSF	9.97 Hz
Characteristic outer ring frequency, BPF0	11.37 Hz
Characteristic inner ring frequency, BPF1	13.63 Hz



Abutment dimensions

da min	55.50 mm
db min	55.50 mm
Da max	74.50 mm
Db max	74.50 mm
r1a max	0.60 mm
ra max	1 mm
D6	61.90 mm

Calculation factors

Equivalent dynamic radial load

$$P = X \cdot Fr + Y \cdot Fa$$

Series			e	Single or DT bearing arrangement				DB or DF arrangement			
				Fa / Fr ≤ e		Fa / Fr > e		Fa / Fr ≤ e		Fa / Fr > e	
				X	Y	X	Y	X	Y	X	Y
70 (NTN & SNR) 72 (NTN & SNR) 78 (NTN) 79 (NTN) 719 (SNR)	15°	0.178	0.38	1	0	0.44	1.47	1	1.65	0.72	2.39
		0.357	0.4				1.4		1.57		2.28
		0.714	0.43				1.3		1.46		2.11
		1.07	0.46				1.23		1.38		2
		1.43	0.47				1.19		1.34		1.93
		2.14	0.5				1.12		1.26		1.82
		3.57	0.55				1.02		1.14		1.66
		5.35	0.56						1.12		1.63
		7.14	0.56				1		1.12		1.63
	25°		0.68			0.41	0.87		0.92	0.67	1.41
	30°		0.8				0.39		0.78		1.24

Equivalent static radial load

$$P_0 = X_0 \cdot Fr + Y_0 \cdot Fa$$

Series			Single or DT bearing arrangement		DB or DF arrangement	
			X ₀	Y ₀	X ₀	Y ₀
70 (NTN & SNR) 72 (NTN & SNR) 78 (NTN) 79 (NTN) 719 (SNR)	15°		0.5	0.46	1	0.92
	25°			0.38		0.76
	30°			0.33		0.66

For single or DT bearing arrangement :

If $P_0 < Fr$, then use $P_0 = Fr$